

November 4(Wed)

09:00~12:00	CGSIC Meeting(Location:202)
09:00~09:05	Opening Mr. John Wilde(<i>Chairman of the CGSIC International Sub-Committee, UK</i>)
09:05~09:20	Welcome Captain Ed. Thiedeman(<i>USCG Navigation Centre and Deputy Chair of CGSIC, U.S.A.</i>)
09:20~09:40	CGSIC Description and Invitation to Participate Mr. John Wilde(<i>Chairman of the CGSIC International Sub-Committee, UK</i>)
09:40~10:10	Coffee Break
10:10~10:30	US Diplomatic Activities in Support of Worldwide GNSS Interoperability Mr. Ray Clore(<i>US Department of State, U.S.A.</i>)
10:30~10:50	GPS Constellation Health and Modernization Mr. Rick Hamilton(<i>USCG and CGSIC Executive Secretariat, U.S.A.</i>)
10:50~11:05	GPS Interference Detection
11:05~11:20	Questions
12:00~13:00	Lunch
13:00~13:20	Opening Ceremony(Location : Samda Hall)
13:05~13:10	Opening Address Dr. Pilho Park(<i>KASI, Korea</i>)
13:10~13:15	Congratulatory Address 1 Dr. Young Gon Lim(<i>KORDI, Korea</i>)
13:15~13:20	Congratulatory Address 2 Prof. Sang Jeong Lee(<i>Chungnam National University, Korea</i>)
13:20~14:00	Keynote Speech (Location: Samda Hall) Chair: Sang Jeong Lee(<i>Chungnam National University, Korea</i>)
13:20~14:00	“Quo Vadis? Where are We Going in Satellite Navigation” Dr. Guenter W. Hein(<i>Head of Galileo Operations and Evolution Department, Germany</i>)
14:00~16:00	Plenary Talk(Location : Samda Hall) Chair: Sang Jeong Lee(<i>Chungnam National University, Korea</i>)
14:00~14:40	“Gyroscope Technology for Inertial Navigation” Prof. Jang Gye Lee (<i>Seoul National Univ., Korea</i>)
14:40~15:20	“GNSS Can We make Easier?” Prof. Miguel M. Romay Merino(<i>GMV, Spain</i>)
15:20~16:00	“U.S. Loran Status” Captain Ed. Thiedeman(<i>USCG Navigation Centre and Deputy Chair of CGSIC, U.S.A.</i>)
16:00~16:30	Coffee Break
16:30~17:50	Status of GNSS(Location : Samda Hall) Chair: Prof. Gyu-In Jee(<i>Konkuk Univ., Korea</i>)
16:30~16:50	“Status of Policy of GPS:Constellation Modernization and U.S. Diplomatic Activities” Mr. Ray Clore(<i>US Department of State, U.S.A.</i>)
16:50~17:10	“GALILEO Program Status Update” Dr. Guenter W. Hein(<i>Head of Galileo Operations and Evolution Department, Germany</i>)
17:10~17:30	“COMPASS/BeiDou Navigation Satellite System Status Updates” Prof. Xingqun ZHAN(<i>Shanghai Jiao Tong University, China</i>)
17:30~17:50	“Status of the QZSS” Mr. Satoshi Kogure(<i>Japan Aerospace Exploration Agency, Japan</i>)

16:30~17:50	Tutorial I, II	Chair : Dr. Deuk Jae Cho(KORDI, Korea)
16:30~17:10	“Introduction to GPS for novice” Dr. Jung Hyun Jo(KASI, Korea)	
17:10~17:50	“GPS Signal structure and positioning algorithm” Dr. Jeong Won Kim(KARI, Korea)	
18:00~19:30	Welcome Reception(Location : Ocean View)	

November 5(Thu)

09:00~10:20	TA1 : GNSS Receiver Technology Chair : Prof. Gyu-In Jee(Konkuk Univ., Korea) Prof. Akio Yasuda(Tokyo Univ., Japan)	202A
09:00~09:20	An FPGA-based GPS Reflectometry Receiver Development <u>Yohei Kawasaki</u> , Takuji Ebinuma and Akio Yasuda (Tokyo University, Japan)	
09:20~09:40	Real-time Carrier Generation for a GNSS Software Receiver <u>Grégoire Waelchli</u> ¹ , Marcel Baracchi-Frei ² , C. Botteron ¹ and P.-A. Farine ¹ (¹ Ecole Polytechnique Fédérale de Lausanne, ² University of Neuchatel, Switzerland)	
09:40~10:00	Software Validation and Verification of a GPS Receiver <u>Deok Won Lim</u> ¹ , Sung Lyong Cho ¹ , Chansik Park ² , Dong-Hwan Hwang ¹ and Sang Jeong Lee ^{1*} (¹ Chungnam National University, ² Chungbuk National University, Korea)	
10:00~10:20	ADC and Quantization Effects in a GMSK-based GNSS Receiver Implementation <u>Jong-Hoon Won</u> ^{1*} , Bernd Eissfeller ¹ , Jean-Jacques Floch ² , Andreas Schmitz-Peiffer ² (¹ University FAF Munich, ² EADS-Astrium, Germany)	
09:00~10:20	TB1: Indoor Navigation and Land Application Chair : Dr. Wan Sik Choi(ETRI, Korea) Dr. Dinesh Manandhar(GNSS Technologies, Japan)	202B
09:00~09:20	Designing the Vehicular Management Information Systems based on Stand-alone GPS Positioning Data <u>C. C. Chang</u> *, C. L. Chiang, M. J. Wu, and K. H. Lai(Ching-Yun University, Taiwan)	
09:20~09:40	Using GPS and GIS in Greater One-horned Rhinoceros Population Assessment and Monitoring in Nepal <u>Nawa Raj Chapagain</u> ¹ and Buddi Sagar Poudel ² (¹ National Trust for Nature Conservation, ² National Parks and Wildlife Conservation, Nepal)	
09:40~10:00	Adaptive Covariance Estimation for Seamless Positioning using Integration of A-GNSS and IEEE 802.15.4a Chirp Spread Spectrum <u>Yong-Soo Kim</u> ¹ , Jung-yun Yeu ¹ , Gyu-In Jee ¹ , Wan Sik Choi ² (¹ Konkuk University, ² Electronics and Telecommunications Research Institute, Korea)	
10:00~10:20	Design and implementation of an integrated dynamic localization system based on 802.15.4 wireless sensor network Bing Wei and <u>Wu Chen</u> (The Hong Kong Polytechnic University, Hong Kong)	
09:00~10:20	TC1: Atmosphere Effect (Ionosphere I) Chair : Dr. Jong-Kyun Jung(KASI, Korea), Prof. Wu Chen(Hongkong Polytech Univ, Hong Kong.)	203
09:00~09:20	A Study on Regional Ionosphere Modeling for e-GPS System <u>Lao-Sheng Lin</u> ^{1*} and Hsiang-Chung Wu ² (¹ National Chengchi University, ² Tainan County Government, Taiwan)	

09:20~ 09:40	Ionospheric Tomography Based on A Small GPS Network in Hong Kong Area Shengyue Ji, <u>Wu Chen</u> , Xiaoli Ding, and Yongqi Chen (<i>The Hong Kong Polytechnic University, China</i>)	
09:40~ 10:00	Comparison of Ionospheric Delays between 3D Ray-Tracing and GPS-TEC Measurements <u>Siti Sarah Nik Zulkifli</u> ^{1*} , Mardina Abdullah ¹ , Ahmad Faizal Mohd Zain ² , and Mahamod Ismail ¹ (¹ <i>Universiti Kebangsaan Malaysia, </i> ² <i>Universiti Tun Hussein Onn Malaysia, Malaysia</i>)	
09:00~ 10:20	TD1: GNSS Augmentation and Applications Chair : Prof. Jiyun Lee (<i>KAIST, Korea</i>)	201A
09:00~ 09:20	Implementation of the Wide Area Differential GPS Master Station Algorithms in Taipei Flight Information Region <u>Shih-Chieh Lu</u> and Shau-Shiun Jan*(<i>National Cheng Kung University, Taiwan</i>)	
09:20~ 09:40	An Operation Test of the GPS Receiver System for Satellite Launch Vehicles using an Aircraft <u>Byung-Moon Kwon</u> *, Ji-Hyeon Moon, Yong-Sul Shin, and Hyung-Don Choi (<i>Korea Aerospace Research Institute, Korea</i>)	
09:40~ 10:00	Surveillance of vehicles in Airside of an Airport using DGPS Technology <u>Jae-Hyun Han</u> and Yo-Sik Kim(<i>The Korea Transport Institute, Korea</i>)	
10:00~ 10:20	CNS/ATM Research and Development Plan in Korea <u>Jae-Hyun Han</u> and Chang-Hwan Kim (<i>The Korea Transport Institute, Korea</i>)	
09:00~ 10:20	Tutorial III,IV Chair : Dr. Jeong-Ho Cho (<i>KARI, Korea</i>)	201B
09:00~ 09:40	GNSS Augmentation system for maritime Sang Hyun Park(<i>KORDI, Korea</i>)	
09:40~ 10:20	GNSS Augmentation system for aviation Eunsung Lee(<i>KARI, Korea</i>)	
10:40~ 12:00	TA2 : GNSS Signal Processing (I) Chair : Dr. Sanguk Lee (<i>ETRI, Korea</i>), Prof. Jinling Wang (<i>UNSW, Australia</i>)	202A
10:40~ 11:00	An Assisted GPS Software Receiver for processing Weak Signals <u>Wu Chen</u> ¹ , Jianfeng Miao ^{1,2} , Yongrong Sun ² , and Jianye Liu ² (¹ <i>Hong Kong Polytechnic University, </i> ² <i>Nanjing University, China</i>)	
11:00~ 11:20	Fraction Sample Effect Compensation Technique for Acquisition of Weak C/A Code Modulated GPS Signals <u>Uzair Ahmad</u> and Wan-Sik Choi (<i>Electronics and Telecommunications Research Institute, Korea</i>)	
11:20~ 11:40	Test of Susceptibility to Spoofing <u>Sung-Hyuck Im</u> and Gyu-In Jee* (<i>Konkuk University, Korea</i>)	
11:40~ 12:00	An Effective Multipath Mitigation Method Under Dominant Multipath Condition <u>Yan Zhang</u> and Nobuaki Kubo(<i>Tokyo University, Japan</i>)	
10:40~ 11:40	TB2: Indoor Navigation and Pseudolite Applications Chair : Dr. Haeyoung Jun (<i>Samsung Electronics Co., Ltd, Korea.</i>), Prof. Chuanrun Zhai (<i>Shanghai Jiao Tong Univ., China</i>)	202B
10:40~ 11:00	Research of Integer Ambiguity Resolution for the Pseudolite-based Indoor Navigation System <u>Xiaoguang Wan</u> , Liduan. Wang, Xingqun Zhan, and Chuanrun Zhai (<i>Shanghai Jiao Tong University, China</i>)	
11:00~ 11:20	Solutions for Implementing Pseudolite Indoor Navigation System by Utilizing New Pulsing Scheme and RFID-based Ambiguity Searching Method <u>Taikjin Lee</u> *, Chongwon Kim, Sanghoon Jeon, Ghangho Kim, Hyungmin So, and Changdon Kee (<i>Seoul National University, Korea</i>)	

11:20~ 11:40	The position-domain GPS/WLAN hybrid position in mobile terminal <u>Young-Su Cho</u> , Byung-Doo Kim, Sung-Jo Yun, Myung-In Jee, and Wan-Sik Choi (<i>Electronics and Telecommunications Research Institute, Korea</i>)	
10:40~ 12:00	TC2: Atmosphere Effect (Ionosphere II) Chair : Dr. Jong-Kyun Jung (KASI, Korea), Prof. Lao-Sheng Lin (National Chengchi Univ., Taiwan)	203
10:40~ 11:00	GPS-Derived Local TEC Mapping over Malaysia during Solar Maximum of Sunspot Cycle 24 <u>Khairul A. Abdullah</u> , Tajul A. Musa, and Shien Kwun Leong (<i>Universiti Teknologi Malaysia, Malaysia</i>)	
11:00~ 11:20	A Study on Predicting Ionospheric Delays Using Artificial Neural Network <u>Yen-Ting Lee</u> and Lao-Sheng Lin (<i>National Chengchi University, Taiwan</i>)	
11:20~ 11:40	Variations of TEC over Different Regions during Ionospheric Storms Mardina Abdullah, <u>Siti Aminah Bahari</u> *, and Baharudin Yatim (<i>Universiti Kebangsaan Malaysia, Malaysia</i>)	
11:40~ 12:00	Modeling the Bias of Abel Inversion Algorithm for Ionospheric Vertical Electron Density (VED) Profile Retrieve Gary Ouyang and <u>Jinling Wang</u> (<i>University of New South Wales, Australia</i>)	
10:40~ 12:00	TD2: Integrity Monitoring Chair : Prof. Young Jae Lee (Konkuk Univ., Korea), Prof. Shau-Shiun Jan (National Cheng Kung Univ., Taiwan)	201A
10:40~ 11:00	Development and Implementation of RAIM to Support the New ATM System <u>Shou-Ju Yeh</u> and Shau-Shiun Jan* (<i>National Cheng Kung University, Taiwan</i>)	
11:00~ 11:20	Performance Analysis of UDRE Estimation for Maritime Differential GPS <u>Sang Hyun Park</u> *, Ki Yeol Seo, Duek Jae Cho, and Sang-Hyun Suh (<i>Korea Ocean Research and Development Institute, Korea</i>)	
11:20~ 11:40	Detection, Identification And Mitigation of Outliers by Solving Correct Observation Equations <u>Hiroshi Isshiki</u> (<i>University of Ulsan, Korea</i>)	
11:40~ 12:00	Analysis on the Limitation of Integrity Monitoring Function for Maritime DGPS <u>Ki-Yeol Seo</u> *, Sang-Hyun Park, Ho-Cheol Jeong, and Sang-Hyun Suh (<i>Korea Ocean Research & Development Institute, Korea</i>)	
10:40~ 12:00	Tutorial III,IV Chair : Dr. Sang Heon Oh (Hanyang Navicom, Korea)	201B
10:40~ 11:20	GPS/INS integrated navigation system Hyung Keun Lee(<i>Korea Aerospace Univ., Korea</i>)	
11:20~ 12:00	GNSS receiver Heung Seok Seo(<i>Hanyang Navicom Co.,Ltd., Korea</i>)	
12:00~13:30	Lunch(Location : Delizia)	

13:30~ 14:50	TA3 : GNSS Signal Processing (II) Chair : Prof. Hyung Keun Lee (Korea Aerospace Univ., Korea), Dr. Nobuaki Kubo (Tokyo University of Marine Science and Technology, Japan)	202A
13:30~ 13:50	An Ambiguity-free BOC(n,n) Signal Tracking Technique <u>Tsai-Ling Kao</u> and Jyh-Ching Juang*(<i>National Cheng Kung University, Taiwan</i>)	
13:50~ 14:10	GPS Receiver Code Tracking Loop Designs Using the Unscented Kalman Filtering Approach <u>Dah-Jing Jwo</u> * and Yi-Jen Chang.(<i>National Taiwan Ocean University, Taiwan</i>)	
14:10~ 14:30	Implementation of a Vector Tracking Loop Receiver for Pseudolite Navigation System Hyoungmin So ¹ *, Taikjin Lee ² , <u>Sanghoon Jeon</u> ² , Chongwon Kim ² , and Changdon Kee ²	

		(¹ SUNWAVETEC Co., Ltd., ² Seoul National University, Japan)	
14:30~ 14:50	Interference mitigation technique using the frequency-domain Capon beam-former <u>Geon Woo Lee</u> , Eun Sup Sim, and Moon Beom Heo (Korea Aerospace Research Institute, Korea)		
13:30~ 15:10	TB3: Timing Applications Chair : Mr. Sung-hoon Yang (KRISS, Korea), Dr. Toshiaki Iwata (National Institute of Advanced Industrial Science and Technology, Japan)		202B
13:30~ 13:50	COMPASS/GPS Dual Mode Timing for CDMA System of China <u>Shan QingXiao</u> , Yang Jun, Chen Jian Yun, and Tang Hong (National University of Defense Technology, China)		
13:50~ 14:10	RESSOX Experiments Using Multiple Navigation Signals as Feedback Control <u>Toshiaki Iwata</u> ^{1*} , Takashi Matsuzawa ¹ , Kumiko Machita ¹ , and Akiyoshi Abei ² (¹ Advanced Industrial Science and Technology, ² Cosmo Research Corporation, Japan)		
14:10~ 14:30	The development of software T&F common view receivers for GNSS satellites <u>Yuki Ito</u> *, Takuya Shinno, Shouta Ishikawa, Ryuei Yamada, and Fujinobu Takahashi, (Yokohama National University, Japan)		
14:30~ 14:50	Time and Frequency Transfer using Loran-C Signals <u>Young-Kyu Lee</u> ^{1*} , Changbok Lee ¹ , Sung-Hoon Yang ¹ , and Young-Jae Kim ² (¹ KRISS, ² Chungbuk National University, Korea)		
14:50~ 15:10	Time Synchronization of Loran Station using TWSTFT Changbok Lee, <u>Sung-hoon Yang</u> , and Young Kyu Lee (Korea Research Institute of Standards and Science, Korea)		
13:30~ 15:10	TC3: Atmosphere Effect (Troposphere) Chair : Prof. Tae-Suk Bae (Sejong Univ., Korea), Prof. Chiang Kai-Wei (National Cheng Kung Univ., Taiwan)		203
13:30~ 13:50	Near-Real-Time Determination of Three-Dimensional Water Vapor Distribution in the Atmosphere Using GPS <u>Jihyun Ha</u> * and Kwan-Dong Park (Inha University, Korea)		
13:50~ 14:10	Real Time Computation Of Precipitable Water Vapour Using Global Positioning System - Data Quality Improvement <u>Reshma Raskar-Phule</u> (Sardar Patel College of Engineering, India)		
14:10~ 14:30	Generation of Meteorological Variables by Artificial Neural Network to Correct the Tropospheric Delay on the GNSS Signal <u>Sung-Wook Jung</u> ^{1*} , Jeongho Baek ^{1,2} , Sungki Cho ¹ , and Jung-Ho Cho ¹ (¹ Korea Astronomy Space Science Institute, ² University of Science and Technology, Korea)		
14:30~ 14:50	Estimation of Absolute Precipitable Water Using the Precise Point Positioning Technique <u>Hsiao-Wen Wu</u> *, Ming Yang, and Kai-Wei Chiang.(National Cheng Kung University, Taiwan)		
14:50~ 15:10	Using GPS Network PPP as Meteorological Sensors in Taiwan: Case Studies of Plum rains and Typhoon Sinlaku <u>Peng Wei-Chih</u> , Yeh Yen-Hua, and Chiang Kai-Wei (National Cheng Kung University, Taiwan)		
13:30~ 15:10	TD3(Domestic): Indoor Navigatoin Chair : Dr. Seong Yun Cho (ETRI, Korea)		201A
13:30~ 13:50	IR-UWB based Friends Searching Method in the Emergency Environments <u>Seong Yun Cho</u> * and Young Woo Choi (Electronics and Telecommunications Research Institute, Korea)		
13:50~ 14:10	Performance Analysis of The IR-UWB Location System <u>Chan-Bock Song</u> and Tae-Kyung Sung (Chung Nam National University, Korea)		
14:10~	A Synchronous Pseudolite System by Single Clock		

14:30	<u>Sanguk Lee</u> , Jae Eun Lee, Cheon Sig Sin, and Jae Hoon Kim (<i>Electronics and Telecommunications Research Institute, Korea</i>)	
13:30~ 14:50	TE3(Domestic): Telematics/LBS Chair : Dr. Jong-Hoon Won (<i>University Federal Armed Forces Munich, Germany</i>)	201B
13:30~ 13:50	Performance Analysis of the GNSS based Autonomous Ground Vehicle for Pointing Position <u>Wooyong Kang*</u> , Eunsung Lee, Jeongho Cho, Moonbeom Heo, and Giwook Nam (<i>Korea Aerospace Research Institute, Korea</i>)	
13:50~ 14:10	Design of High Accuracy GPS/DR Integrated Navigation System for Lane Departure Warning <u>Jeong Won Kim</u> , Soon-Chul Park, Moon Beom Heo, Gi Wook Nam, and Eun-Sup Sim (<i>Korea Aerospace Research Institute, Korea</i>)	
14:10~ 14:30	Readers Arrangement and TDOA DOP of Position Tracking System for Logistic Vehicles <u>Hee Won Kang</u> , Deok Won Lim, Dong-Hwan Hwang and Sang Jeong Lee (<i>Chungnam National University, Korea</i>)	
14:30~ 14:50	Implementation of WiBro Simulator for Geo-location <u>Ji-Won Park</u> and Tae-Kyung Sung*(<i>Chungnam National University, Korea</i>)	
15:10~16:10	Poster Session (1) & Coffee Break	

15:10- 16:10	Poster I Chair : Prof. Tae-Kyung Sung (<i>Chungnam National Univ., Korea</i>) Prof. Dong-Hui Yu (<i>Catholic University of Pusan, Korea</i>)	2F Lobby
PS01	Suppression of Non-stationary Sinusoidal GNSS Interference Using Frequency Domain K-median Excision Filtering <u>Jun-O Kim</u> ¹ , Jong-Chul Cho ² , and Ki Won Song ¹ (¹ <i>Agency for Defense Development, </i> ² <i>Hanyang Navicom Co., Ltd, Korea</i>)	
PS02	Development of a Dual-mode GPS/Galileo Receiver Platform <u>Chih-Herng Wu</u> , Yu-Hsuan Chen, Tsai-Ling Kao, and Jyh-Ching Juang (<i>National Cheng Kung University, Taiwan</i>)	
PS03	An efficient protocol for friend identification and localization in IR-UWB <u>Young Woo Choi</u> and Seong Yun Cho (<i>Convergence Research Department, Electronics and Telecommunications Research Institute, Korea</i>)	
PS04	Evaluation of GPS Time Transfer Precision with IGS Ultra Rapid Products and KARAT <u>Tadahiro Gotoh</u> ¹ , Thomas Hobiger ¹ , and Ryuichi Ichikawa ² (¹ <i>National Institute of Information and Communications Technology, </i> ² <i>Kashima Space Research Center, NICT, Japan</i>)	
PS05	Design And Implementation Of Trellis Coded Modulation Scheme To Improve The BER Of GPS Signal Rajkumar Goswami ¹ , G Sasi Bhushana Rao ¹ , Kancharana Harini ² , <u>Vinod Naik Bhukya</u> ¹ , and Ch.Usha Kumari ¹ (¹ <i>Andhra University, </i> ² <i>Indian Institute of Information Technology Hyderabad, India</i>)	
PS06	Investigation of the Data Quality at Dokdo Integrity Monitoring Station <u>In-Kwan Park</u> , Sungki Cho, Byung-Kyu Choi, Mansoo Choi, and Jung-Ho Cho (<i>Korea Astronomy and Space Science Institute, Korea</i>)	
PS07	Fault Detection of TDOA Measurements using Hypothesis Test <u>Byung-Doo Kim</u> , Young-Su Cho, Sung-Jo Yun, Myung-In Jee, and Wan-Sik Choi (<i>Electronics and Telecommunications Research Institute, Korea</i>)	
PS08	Mobile Transaction System for Location-Based Services by Using a Wireless Card Reader Module with Integrated GPS <u>Ick Chang Choi</u> , Young Cheol Kim, and Hyun Deok Kim (<i>Kyungpook National University, Korea</i>)	
PS09	Location-Based Service Employing Push-to-Talk Service <u>Sang Tae Kim</u> , Gi Min Kim, Hong Kyun Im, and Hyun Deok Kim	

		(Kyungpook National University, Korea)
PS10	Analysis for the GNSS Tracking plan by Future Korean SLR System <u>Jung Hyun Jo</u> (Korea Astronomy and Space Science Institute, Korea)	
PS11	Design of a Reference System for Urban Facility Management based on Geographic Information System <u>JaeJun Yoo</u> and <u>KyoungOk Kim</u> (Electronics and Telecommunications Research Institute, Korea)	
DP01	SOM based Integrity Monitoring in the Simultaneous Multiple Satellites Failure <u>Jeongho Cho</u> , Eunsung Lee, Wooyoung Kang, and Moon Beom Heo (Korea Aerospace Research Institute, Korea)	
DP02	Multipath Interference Cancellation Technique for High Precision Tracking in GNSS Receiver <u>Byeong-Chan Jo</u> ¹ , <u>Sungmin Park</u> ² , <u>Hyunsu Hong</u> ² , <u>Jinwon Kim</u> ² and <u>Sunwoo Kim</u> ¹ (¹ Hanyang University, ² Samsung Electronics, Korea)	
DP03	Analysis of the Real-Time and Post-processed Data of KSLV-I GPS Receiver System on the Flight Test using an Aircraft <u>Ji-Hyeon Moon</u> *, Byung-Moon Kwon, Yong-Sul Shin, and Hyung-Don Choi (Korea Aerospace Research Institute, Korea)	
DP04	Hybrid RSSI/TOA Method for Tracking Mobility <u>Dong-Seon Kim</u> and Sunwoo Kim(Hanyang University, Korea)	

16:10~ 17:50	TA4 : System and Performance Analysis Chair : Dr. Jeong-Ho Cho (KARI, Korea) Mr. Satoshi Kogure (JAXA, Japan)	202A
16:10~ 16:30	GPS/Galileo/QZSS Radio Frequency Compatibility Analysis in Asia-Pacific Region <u>Wei Liu</u> ¹ *, <u>Chuan Run Zhai</u> ¹ , <u>Xing Qun Zhan</u> ¹ , <u>Yan Hua Zhang</u> ¹ , and <u>Chun Ming Fan</u> ² (¹ Shanghai Jiao Tong University, ² Tokyo University, China)	
16:30~ 16:50	Performance Analysis of Precise Positioning for Combined GPS and GLONASS in Urban Area <u>Byung-Hyun Lee</u> ¹ , <u>Seung-Hwan Yoo</u> ¹ , <u>Gyu-In Jee</u> ¹ , <u>Jun-O Kim</u> ² , and <u>Joong-Hyup Ko</u> ³ (¹ Konkuk University, ² Ucomm Technology Co., Ltd, ³ Kyung-Bong Co., Ltd., Korea)	
16:50~ 17:10	Effect of Quasi Zenith Satellite (QZS) on GPS Positioning <u>Tomoji Takasu</u> , <u>Takuji Ebinuma</u> , and <u>Akio Yasuda</u> (Tokyo University, Japan)	
17:10~ 17:30	An Efficient Approach for Developing an Advanced Regional Navigation Satellite System <u>Maria Dolores Laínez Samper</u> , <u>Miguel M. Romay Merino</u> , and <u>Ignacio Alcantarilla Medina</u> (GMV, Spain)	
16:10~ 17:50	TB4: Survey/Mapping/GIS Chair : Prof. Kwan-Dong Park (Inha Univ., Korea), Prof. Gethin W. Roberts (The University of Nottingham, United Kingdom)	202B
16:10~ 16:30	The Performance Analysis of LC and TC Low Cost MEMS IMU/GPS POS System for Van Based MMS Applications <u>Yun-Wen Huang</u> , <u>Meng-Lun Tsai</u> *, and <u>Kai-Wei Chiang</u> (National Cheng Kung University, Taiwan)	
16:30~ 16:50	Feasibility of integrated Locata and GNSS for Engineering Work Application <u>Lukasz K Bonenberg</u> , <u>Gethin W. Roberts</u> *, <u>Craig M. Hancock</u> *, <u>Oluropo Ogundipe</u> *, and <u>Jae Kang Lee</u> * (The University of Nottingham, United Kingdom)	
16:50~ 17:10	A study on the suitability of Locata operation for Bridge Deformation Monitoring <u>Jae-Kang Lee</u> , <u>Gethin W. Roberts</u> , <u>Oqundipe Oluropo</u> , <u>Craig M. Hancock</u> and <u>Lukasz Bonenberg</u> (The University of Nottingham, United Kingdom)	
17:10~ 17:30	Study on Vertical Alignment Maintenance Technique using GNSS in Skyscraper <u>Eunchurn Park</u> ¹ , <u>Yu-Seung Kim</u> ¹ , <u>Joong-Yub Lee</u> ¹ , <u>Jun-Sung Choi</u> ¹ *, <u>Yeon-Back Jung</u> ² , and <u>Won-Kyun Seok</u> ² , <u>Kwang-Soo Jung</u> ² , <u>Soon-Jeon Park</u> ² , <u>Joo-Ho Lee</u> ² (¹ Korea Maintenance Co., Ltd., ² Lotte Engineering & Construction, Korea)	

17:30~ 17:50	The Investigation of Calibration Methodology for a Low Cost Land Vehicle Mobile Mapping System <u>Yu-Hua Li</u> *, Kai-Wei Chiang, and Jiann-You Rau(<i>National Cheng Kung University, Taiwan</i>)	
16:10~ 17:50	TC4: POD (Precise Orbit Determination) Chair : Dr. Sungki Cho (KASI, Korea), Prof. Marek Ziebart (UCL, UK)	203
16:10~ 16:30	GNSS-Based Orbit Determination for Highly Elliptical Orbit Satellites Li Qiao ^{1,2*} , <u>Samsung Lim</u> ¹ , Chris Rizos ¹ , and Jianye Liu ² (¹ <i>University of New South Wales, </i> ² <i>Nanjing University of Aeronautics and Astronautics, Australia</i>)	
16:30~ 16:50	Analysis of Precision GPS Orbits Based on the Dynamic Approach <u>Tae-Suk Bae</u> ¹ and Jay Hyoun Kwon ² (¹ <i>Sejong University, </i> ² <i>The University of Seoul ,Korea</i>)	
16:50~ 17:10	KOMPSAT-2 Precise Orbit Determination Using GPS Single Frequency Data <u>Dae-Won Chung</u> ¹ , Ok-Chul Jung ¹ , Jong-Yeoun Choi ¹ , and Sang-Jeong Lee ^{2*} (¹ <i>Korea Aerospace Research Institute, </i> ² <i>Chungnam National University, Korea</i>)	
17:10~ 17:30	High Precision Radiation Force Modelling in GNSS: Orbit Prediction, Orbit Determination and the GPS-SLR Bias <u>Marek Ziebart</u> ¹ , Ant Sibthorpe ² , and Peter Stacey ¹ (¹ <i>University College London, </i> ² <i>NASA Jet Propulsion Laboratory, United Kingdom</i>)	
16:10~ 17:50	TD4(Domestic): GNSS Receiver/SDR Chair : Dr. Taikjin Lee (<i>Seoul National Univ., Korea</i>)	201A
16:10~ 16:30	The Development of Signal Processing Algorithms for GPS/Galileo Signals <u>Jin-Seok Kim</u> , Sung-Wook Moon, Se-Hwan Kim, and Young-Baek Kim (<i>Hanyang Navicom Co., Ltd., Korea</i>)	
16:30~ 16:50	Performance Evaluation of a Loran Station <u>Young-Kyu Lee</u> ^{1*} , Chang-Bok Lee ¹ , Sung-Hoon Yang ¹ , and Young-Jae Kim ² (¹ <i>KRISS, </i> ² <i>Chungbuk National University, Korea</i>)	
16:50~ 17:10	Enhancement of Positioning Accuracy for Weak GPS Signals <u>Ji-Hee Park</u> and Tae-Kyung Sung*(<i>Chungnam National University, Korea</i>)	
17:10~ 17:30	The Development of Multi-Frequency (GPS L1/Galileo E1/E5a) GNSS Software Receiving Platform in Post-Processing environment Sang-Hoon Jeon ^{1*} , Hyoung-Min So ¹ , Taek-Jin Lee ¹ , Ghang-Ho Kim ¹ , Seung-Il Jeon ¹ , <u>Jong-won Kim</u> ¹ , Chang-Don Kee ¹ , Young-Su Cho ^{2*} , Wan-Sik Choi ² , Sang-Uk Lee ² , and Jae-Hoon Kim ² (¹ <i>Seoul National University, </i> ² <i>Electronics and Telecommunications Research Institute, Korea</i>)	
17:30~ 17:50	The Development of Component-based GNSS Software Receiver <u>Tae Hee Kim</u> , Jae Eun Lee, Sanguk Lee, and Jae Hoon Kim (<i>Electronics and Telecommunications Research Institute, Korea</i>)	
16:10~ 17:50	TE4(Domestic): Anti-jamming Chair : Dr. Sungmin Park (<i>Samsung Electronics Co., Ltd., Korea</i>)	201B
16:10~ 16:30	Squaring-loss Considering Signal Interference in Multiple Access Systems <u>Seung-Hun Song</u> * and Tae-Kyung Sung(<i>Chungnam National University, Korea</i>)	
16:30~ 16:50	Design of Interference Location System Using Multiple GNSS Receivers <u>Byeong-Gyun Kim</u> ^{1*} , Young Bum Park ² and Se Hwan Kim ¹ (¹ <i>Hanyang Navicom Co., Ltd., </i> ² <i>Agency for Defense Development, Korea</i>)	
16:50~ 17:10	The design and analysis of CRPA STAP algorithm for GPS anti-jamming <u>Kihoon Lee</u> *, Seung Kwan Ahn, and Ki Won Song (<i>Agency for Defense Development, Korea</i>)	
18:00~20:00	Banquet(Location : Halla Hall)	

November 6 (Fri)

09:00~ 10:20	FA1 : Inertial System and Integration (I) Chair : Prof. Hyungkyu Lee (<i>Changwon National Univ., Korea</i>), Prof. Dah-Jing Jwo (<i>National Taiwan Ocean Univ., Taiwan</i>)	202A
09:00~ 09:20	Compensation Method on the Installation Errors of the IMU Based on Linear Accelerometers <u>Wu Junwei</u> and Jia Bo(<i>Harbin Engineering University, China</i>)	
09:20~ 09:40	Application of Marginalized Particle Filter in INS Initial Alignment <u>Jian Xiong</u> , Jianye Liu, Jizhou Lai, and Zhi Xiong (<i>Nanjing University of Aeronautics and Astronautics, China</i>)	
09:40~ 10:00	High Fidelity Simulation Analysis of EKF Based Tightly Coupled GPS/INS <u>Ping Ye*</u> , Chuanrun Zhai, Xingqun Zhan, and Yanhua Zhang_(<i>Shanghai Jiao Tong University, China</i>)	
10:00~ 10:20	Adaptive Interacting Multiple Model Unscented Kalman Filtering for GPS/INS Navigation <u>Mu-Yen Chen</u> , Dah-Jing Jwo*, and Mong-Shu Lee (<i>National Taiwan Ocean University, Taiwan</i>)	
09:00~ 10:20	FB1: Space Geodesy / Earth Science (I) Chair : Dr. Jong-Uk Park (<i>KASI, Korea</i>),	202B
09:00~ 09:20	Improved Performance of Long Baseline GPS/GLONASS RTK <u>Hideki Yamada</u> , Tomoji Takasu, Nobuaki Kubo, and Akio Yasuda (<i>Tokyo University of Marine Science and Technology, Japan</i>)	
09:20~ 09:40	A Linearized Approach for Ambiguity Resolution Applied to the GNSS Compass Problem: Experimental Results G. Giorgi ^{1*} , P.J.G. Teunissen ^{1,2} , P.J. Buist ¹ , and L. Huisman ² (¹ <i>Delft University of Technology</i> , ² <i>Curtin University of Technology, Netherlands</i>)	
09:40~ 10:00	Analysis of the Vertical Crustal Deformation around the Korean Peninsula using Permanent GPS Stations and Tide Gauges <u>Kyeong Hui Kim*</u> , and Kwan-Dong Park(<i>Inha University, Korea</i>)	
10:00~ 10:20	Particle Filtering for Denoising in Deformation Data Analysis <u>Nanshan Zheng</u> ^{1,2} , Jingxiang Gao ¹ , and Shubi Zhang ¹ (¹ <i>China University of Mining and Technology</i> , ² <i>Kyoto University, Japan</i>)	
09:00~ 10:20	FC1: Hybrid Receiver Technology Chair : Dr. Young Baek Kim (<i>Hanyang Navicom Co., Ltd, Korea</i>), Prof. Jyh-Ching Juang (<i>National Cheng Kung Univ., Taiwan</i>)	203
09:00~ 09:20	Development of the low-cost RTK-GPS receiver with an open source program package RTKLIB <u>Tomoji Takasu</u> and Akio Yasuda*(<i>Tokyo University of Marine Science and Technology, Japan</i>)	
09:20~ 09:40	Precise Positioning Algorithm for Low-Cost Highly-Dynamic GPS receivers toward Ubiquitous Transportation <u>Hee Sung Kim</u> and Hyung Keun Lee*(<i>Korea Aerospace University, Korea</i>)	
09:40~ 10:00	Software-Based Loran-C Signal Processing Using Half Cycle Peak Ratio <u>Jun-Hyuck Im</u> ¹ , Sung-Hyuck Im ¹ , Woo-Hyun Kim ² , Ha-Yeong Song ¹ , and Gyu-In Jee ^{1*} (¹ <i>Konkuk University</i> , ² <i>Seoul National University, Korea</i>)	
10:00~ 10:20	Test Requirements When Developing or Assessing Multi-GNSS Receivers <u>Andrew Addy</u> and Jianxin Li(<i>Spirent Communications, United Kingdom</i>)	
09:00~ 10:20	FD1(Domestic): DGNSS Chair : Dr. Byungwoon Park (<i>Seoul National Univ., Korea</i>)	201A
09:00~ 09:20	The Performance Analysis of SV. Clock Error Interpolation Algorithm for Precise Point Positioning <u>Ho Cheol Jeong*</u> , Sang Hyun Park, and Duek Jae Cho (<i>Korea Ocean Research and Development Institute, Korea</i>)	
09:20~	Korean Regional Area Augmentation System (RAAS) for Re-capitalizing the NDNSS infra	

09:40	structure <u>Ho Yun</u> ¹ , Byungwoon Park ¹ , Inmo Jang ¹ , Junesol Song ¹ , Changdon Kee ¹ , Deuk-Jae Cho ² , Sang-Hyun Park ² , and Sang-Hyun Suh ² (¹ Seoul National University, ² Korea Ocean Research & Development Institute, Korea)	
09:40~ 10:00	Adaptive DGNSS Correction Generation Algorithm for High Altitude User Ho Yun ¹ , Byungwoon Park ¹ , <u>Inmo Jang</u> ¹ , Junesol Song ¹ , Changdon Kee ¹ , and Kihoon Lee ² (¹ Seoul National University, ² Agency for Defense Development, Korea)	
10:00~ 10:20	A Precise Time Transfer Scheme Using the Maritime DGPS <u>Dong jin Shin</u> ¹ , Sang Wook Hwang ¹ , Heon Ho Choi ¹ , Young Hoon Han ¹ , Sung-Hun Yang ² , Chansik Park ³ , and Sang Jeong Lee ^{1*} (¹ Chungnam National University, ² Korea Research Institute of Standards and Science, ³ Chungbuk National University, Korea)	
09:00~ 10:20	FE1(Domestic): GNSS Applications (1) Chair : Dr. Jeong Won Kim (Korea Aerospace Research Institute., Korea)	201B
09:00~ 09:20	Operation of the GPS Receiver System for KSLV-I on the Launch Pad at Naro Space Center <u>Byung-Moon Kwon</u> *, Ji-Hyeon Moon, Yong-Sul Shin, and Hyung-Don Choi (Korea Aerospace Research Institute, Korea)	
09:20~ 09:40	Fault Detection Method of the Inertial Sensors in the Satellite Using Principal Component Analysis <u>Won Hee Lee</u> , Jun Kyu Lim, and Chan Gook Park* (Seoul National University, Korea)	
09:40~ 10:00	Evaluation of Flight and Landing GPS Data Based on Position Domain Double-Differencing Hatch Filter Hee Sung Kim ¹ , Young Jun Lee ¹ , <u>Je-Young Lee</u> ¹ , Jung Min Joo ² , Moon Beom Heo ² , and Hyung Keun Lee ^{1*} (¹ Korea Aerospace University, ² Korea Aerospace Research Institute, Korea)	
10:00~10:40	Coffee Break	

10:40~ 12:00	FA2 : Inertial System and Integration (II) Chair : Prof. Dong-Hwang Hwang (Chungnam National Univ., Korea) Prof. Jia Bo (Harbin Engineering Univ., China)	202A
10:40~ 11:00	A vehicle Navigation System with GPS and Low-cost Inertial Sensors Shiyu Zhang, <u>Wu Chen</u> , Zhilin Li, and William Lam(Hong Kong Polytechnic University, China)	
11:00~ 11:20	Improving Performance of a Pedestrian Navigation System using a Robust Kalman Filter <u>Rui Xu</u> ^{1,2} , Wu Chen ¹ , Jianye Liu ¹ , Zhilin Li ¹ , and Yongrong Sun ² (¹ Hong Kong Polytechnic University, ² Nanjing University of Aeronautics and Astronautics, China)	
11:20~ 11:40	The Development of Self-Growing Neural Network Embedded Attitude Determination Scheme for a MEMS IMU/GPS Integrated System Hsiu-Wen Chang, <u>Kuan-Yun Chen</u> *, and Kai-Wei Chiang (National Cheng-Kung University, Taiwan)	
11:40~ 12:00	Design and implementation of an INS-aided tightly integrated GNSS/SINS navigation System <u>Rongbing Li</u> , Jianye Liu, Li Wen, and Yongrong Sun (Nanjing University of Aeronautics and Astronautics, China)	
10:40~ 12:00	FB2: Space Geodesy / Earth Science (II) Chair : Dr. Jung Hyun Jo (KASI, Korea), Dr. Sungki Cho (KASI, Korea)	202B
10:40~ 11:00	Establishment of GPS Monitoring system over the coastal zone in China <u>Yanxiong Liu</u> *, Xinhua Zhou, Yikai Feng, and Huayi Zhang(SOA, China)	
11:00~ 11:20	Detection of Ocean Tide Loading Constituents using GPS <u>Jihye Won</u> *, Kwan-Dong Park(Inha University, Korea)	

11:20~ 11:40	Analysis of Reflected GPS Signal to Develop Algorithms for Land and Sea Area Discrimination <u>Daeyun Shin</u> [*] , Manadhar Dinesh, and Ryosuke Shibasaki (<i>The University of Tokyo, Japan</i>)	
10:40~ 12:00	FC2: Enhanced Loran Chair : Captain Edwin Thiedeman (U.S. Coast Guard, <i>U.S.A.</i>), Mr. Sung-hoon Yang (<i>KRISS, Korea</i>)	203
10:40~ 11:00	Position Determination in Loran-C Software Receiver Using Unscented Kalman Filter <u>Woo-Hyun Kim</u> ^{1*} , Jun-Hyuck Im ² , Gyu-In Jee ² , and Jang-Gyu Lee ¹ (¹ <i>Seoul National University</i> , ² <i>Konkuk University, Korea</i>)	
11:00~ 11:20	Comparison of Predicted and Measured ASF in Korea <u>Mi Young Shin</u> ¹ , Sang Wook Hwang ¹ , Dong-Hui Yu ² , Chansik Park ³ , Sung-Hoon Yang ⁴ , and Sang Jeong Lee ^{1*} (¹ <i>Chungnam National University</i> , ² <i>Catholic University of Pusan</i> , ³ <i>Chungbuk National University, Korea</i> , ⁴ <i>Korea Research Institute of Standards and Science</i>)	
11:20~ 11:40	ASF Validation Technique of Loran Signal <u>Sung-hoon Yang</u> ¹ , Changbok Lee ^{1*} , Young Kyu Lee ^{1**} , and Sang Jeong Lee ² (¹ <i>Korea Research Institute of Standards and Science</i> , ² <i>Chungnam National University, Korea</i>)	
11:40~ 12:00	Improved ASF Correction Methods for eLoran in a Mountainous Area <u>Sang Wook Hwang</u> ¹ , Mi Young Shin ¹ , Dong-Hui Yu ² , Chansik Park ³ , Chang-Bok Lee ⁴ and Sang Jeong Lee ^{1*} (¹ <i>Chungnam National University</i> , ² <i>Catholic University of Pusan</i> , ³ <i>Chungbuk National University</i> , ⁴ <i>Korea Research Institute of Standards and Science, Korea</i>)	
10:40~ 12:00	FD2(Domestic): Algorithms Chair : Prof. Gyu-In Jee (<i>Konkuk Univ., Korea</i>)	201A
10:40~ 11:00	Design of ASF Measurements System in the Field <u>Sung-hoon Yang</u> ¹ , Chang Bok Lee ^{1*} , Young Kyu Lee ^{1**} , and Sang Jeong Lee ² (¹ <i>Korea Research Institute of Standards and Science</i> , ² <i>Chungnam National University, Korea</i>)	
11:00~ 11:20	The Detection and Isolation of the Abnormal Satellite Using Range Residual and Position Comparison <u>Yong-Woon Ahn</u> , Young Jae Lee [*] , and Sangkyung Sung(<i>Konkuk University, Korea</i>)	
11:20~ 11:40	Development of GPS/INS Fault Detection Algorithm Based RAIM <u>Jang Sik Yoo</u> , Sangkyung Sung, and Young Jae Lee [*] (<i>Konkuk University, Korea</i>)	
11:40~ 12:00	Implementation of Testable SDINS Software <u>Sung Lyong Cho</u> ¹ , Deok Won Lim ¹ , Sul Gee Park ¹ , Chansik Park ² , Dong-Hwan Hwang ¹ , and Sang Jeong Lee ^{1*} (¹ <i>Chungnam National University</i> , ² <i>Chungbuk National University, Korea</i>)	
10:40~ 12:00	FE2(Domestic): GNSS Applications (2) Chair : Dr. Sang Hyun Park (<i>Korea Ocean Research & Development Institute, Korea</i>)	201B
10:40~ 11:00	Weighted Correction Method of GBAS Pseudorange using Real Data of Jeju International Airport <u>Eunsung Lee</u> , Moon Beom Heo, and Gi-Wook Nam [*] (<i>Korea Aerospace Research Institute, Korea</i>)	
11:00~ 11:20	Improvement of Hanvit for Next Generation Navigation System <u>Ghangho Kim</u> ^{1*} , Taikjin Lee ¹ , Changdon Kee ¹ , Hyeongsang Lee ² , Sunghun Lim ² and Youngahn Lee ² (¹ <i>Seoul National University</i> , ² <i>ANSE Technologies, Korea</i>)	
11:20~ 11:40	Performance analysis of TDLS relative navigation system <u>Heon Ho Choi</u> ¹ , Sang Wook Hwang ¹ , Mi Young Shin ¹ , Jeon Sang Jang ² , Chansik Park ³ and Sang Jeong Lee ^{1*} (¹ <i>Chungnam National University</i> , ² <i>Agency for Defense Development</i> , ³ <i>Chungbuk National University, Korea</i>)	
11:40~ 12:00	Vision/DR(Encoder, Gyro) Integrated Indoor Navigation System Using Kinematic Characteristic of a Mobile Robot <u>Sul Gee Park</u> and Dong-Hwan Hwang(<i>Chungnam National University, Korea</i>)	
12:00~13:30	Poster session(II) & Lunch	

12:00~ 13:30	Poster II Chair : Dr. Jung Hyun Jo(KASI, Korea) Dr. Dongho Shin(ADD, Korea)	2F Lobby
PS01	Analyzing and Estimating of GPS Medium-Range Kinematic Positioning in Taiwan Area <u>Hornng-Yue Chen</u> ¹ , Shui-Bei Yu ¹ , He-Chin Chen ² , Yao-Hsien Tseng ² , and Yao-Hsien Tseng ² <i>(¹Academia Sinica, ²Ministry of Interior, Taiwan)</i>	
PS02	Development of a local Ionospheric Model for Improving RTK-GPS Positioning <u>Byung-Kyu Choi</u> ¹ , Sung-Ki Cho ¹ , and Sang-Jeong Lee ² <i>(¹Korea Astronomy Space Science Institute, ²Chungnam National University, Korea)</i>	
PS03	GPS-DR Integrated Navigation System for Car Navigation <u>Kwang-Hoon Kim</u> *, Jong-Hwa Song, and Gyu-In Jee <i>(Konkuk University, Korea)</i>	
PS04	Operation of the Radio Occultation Mission in KOMPSAT-5 <u>Man-Soo Choi</u> , Woo-Kyung Lee, Sung-Ki Cho, and Jong-Uk Park <i>(Korea Astronomy and Space Science Institute, Korea)</i>	
PS05	The Novel System of IGS Global Data Center in KASI <u>Sung-Wook Jung</u> *, Sungki Cho, In Kwan Park, and Jung-Ho Cho <i>(Korea Astronomy Space Science Institute, Korea)</i>	
PS06	Performance Analysis of the Batch Estimation based on the Unscented Transformation <u>Eunseo Park</u> ¹ , Byung-Kyu Choi ¹ , Sungki Cho ¹ , Jung-Ho Cho ¹ , Jong-Uk Park ¹ , Sang-Young Park ¹ , and Kyu-Hong Choi ² <i>(¹Korea Astronomy & Space Science Institute, ²Yonsei Uni., Korea)</i>	
PS07	A Study on the World Geodetic System-84 Manual for Korean System <u>Jae-Hyun Han</u> and Ja-Young Yoon <i>(The Korea Transport Institute, Korea)</i>	
PS08	Development of INS-Aided GPS Tracking Loop and Flight Test Evaluation <u>Toshiaki Tsujii</u> ¹ , Takeshi Fujiwara ¹ , Yoshimitsu Sukanuma ¹ , Hiroshi Tomita ¹ , and Ivan Petrovski ² <i>(¹Japan Aerospace Exploration Agency, ²iP-Solutions, Japan)</i>	
PS09	A Study on Optimal Technical Factors of Underground Structure Field Support System based on Integrated Technique of VI-GNSS <u>Yong-Gu Jang</u> and Il-Hyeon Nam <i>(Korea Institute of Construction Technology, Korea)</i>	
PS10	Accuracy of Large Block Adjustment with UltraCamX Image of Digital Aerial Camera <u>Jae-One Lee</u> ¹ , Young-Min Kim ² , and Gwang-Jae We ³ <i>(¹Dong-A University, ²Sam Ah Survey Co., Ltd., ³Hanjin Information System and Telecommunication Co., Ltd, Korea).</i>	
PS11	Analysis of Ionosphere TEC Variation during the Solar Eclipse of July 22, 2009 using GPS Permanent Stations Data <u>He Huang</u> , Hong-Sic Yun, Hyung-Lock Bae, and Tae-Jun Jeong <i>(Department of Civil, Architectural and Environmental System Engineering, Sungkyunkwan University, Korea)</i>	
PS12	Control Algorithm Design for Phase Stability of Korean Standard Frequency <u>Deokhee Han</u> ¹ , Seunghoon Yang ² , Daihyuk Yu ² , and Chansik Park ¹ <i>(¹Chungbuk National University, ²Korea Astronomy Space Science Institute, Korea)</i>	
PS13	A multi-frequency approach to GNSS relative positioning during high ionosphere activity periods <u>Yi-Teng Sun</u> and Ming Yang* <i>(National Cheng Kung University, Taiwan)</i>	
PS14	A Phase-only Triple-Frequency Algorithm for GNSS kinematic Positioning <u>Feng-Yu Chu</u> and Ming Yan	

		(National Cheng Kung University, Taiwan)
PS15	A Feasibility Study of GPS/Galileo Single-frequency RTK Positioning <u>Li-Yang Shen</u> and Ming Yang(National Cheng Kung University, Taiwan)	
DP01	First Approach of GPS L5 Signal Processing Board for GNSS Ground Sensor Station <u>Jaehyun Kim</u> , Chensig Shin, Sanguk Lee, and Jae Hoon Kim (Electronics and Telecommunications Research Institute, Korea)	
DP02	Analysis of LEO satellite precise orbit determination according to IGS clock information <u>Yoola Hwang*</u> , Byoung-Sun Lee, Sanguk Lee, and Jaehoon Kim (Electronics and Telecommunications Research Institute, Korea)	
DP03	Airborne Monitoring Algorithm For Ionosphere Anomaly Detection At A Regional Area <u>Jung-Min Joo</u> , Jeong-Ho Cho, and Moon-Beom Heo* (Aerospace Research Institute, Korea)	

13:30~ 15:10	FA3 : Inertial System and Integration (III) Chair : Prof. Hyung Keun Lee (Korea Aerospace Univ., Korea), Prof. Yongrong Sun(Nanjing University of Aeronautics and Astronautics, China)	202A
13:30~ 13:50	Network Based GPS/INS Integration: Concept and Performance Analysis <u>Hungkyu Lee</u> ¹ , Binghao Lee ² , Yong Lee ² , and Young-Jin Lee ³ (¹ Changwon National University, ² University of New South Wales, ³ Kyungil University, Korea)	
13:50~ 14:10	Anti-jamming Performance Test for Tightly Coupled GPS/INS Integrated Navigation System <u>Dongho Shin</u> ¹ , Deok Bae Park ¹ , Sang Heon Oh ² , Seok Bo Son ² , IL Young Jeong ² , Seung Bok Kwon ³ , nd Jeong Ho Ro ³ (¹ Agency for Defense Development, ² Hanyang Navicom Co., Ltd., ³ LIG Nex1 Co., Ltd., Korea)	
14:10~ 14:30	The Application of Adaptive Kalman Filter in a Two-Phase Integration Scheme of GPS/INS Songlai Han ^{1,2*} , Jinling Wang ² , Nathan Knight ² , and John Ding ² (¹ National University of Defense Technology, ² The University of New South Wales, Australia)	
13:30~ 15:10	FB3: PPP/RTK Applications Chair : Dr. Samsung Lim(UNSW, Australia), Dr. Yukihiro Kubo(Ritsumeikan Univ., Japan)	202B
13:30~ 13:50	Instantaneous GNSS-based Kinematic Relative Positioning and Attitude Determination using Multi-Antenna Configurations <u>Peter J. Buist</u> ^{1*} , Peter J. G. Teunissen ^{1,2} , Gabriele Giorgi ¹ , and Sandra Verhagen ¹ (¹ Delft University of Technology, ² Curtin University of Technology, Netherlands)	
13:50~ 14:10	Estimation Methods of Satellite Orbit and Clock Errors Based on GNSS Regression Models <u>Yukihiro Kubo</u> , Tomohiro Yanase, Shinichi Otsuki, and Sueo Sugimoto(Ritsumeikan University, Japan)	
14:10~ 14:30	Long Baseline GNSS Relative Positioning with Estimating Zenith Delays of Ionosphere and Tropospheric Delays <u>Tomohiro Yanase</u> ¹ , Seigo Fujita ² , Hisaya Tanaka ¹ , Yukihiro Kubo ^{1*} , and Sueo Sugimoto ¹ (¹ Ritsumeikan University, ² Electronic Navigation Research Institute, Japan)	
14:30~ 14:50	Improving Performance of GNSS Ambiguity Resolution Using Kalman Filter <u>Hee Hak Yun</u> ¹ , Deokhee Han ¹ , Il Kyu Park ² and Chansik Park ^{1*} (¹ Chungbuk National University, ² Hanyang Navicom Co., Ltd., Korea)	
14:50~ 15:10	The Compact Network RTK method: An effective solution to reduce GNSS temporal and spatial decorrelation error <u>Byungwoon Park*</u> and Changdon Kee(Seoul National University, Korea)	
13:30~ 15:10	FD3(Domestic): Survey Chair : Prof. Kwan-Dong Park(Inha University, Korea)	201A
13:30~ 13:50	Evaluation of Positioning Availability and Accuracy Improvement Under the Integrated GNSS Environment	

	<u>Hye-In Kim</u> *, Kwan-Dong Park, Chang-Moon Lee, and Ho-Seok Lee (<i>Inha University, Korea</i>)	
13:50~ 14:10	Klobuchar Model Coefficients Estimation and Accuracy Analysis <u>Chang-Moon Lee</u> *, Kwan-Dong Park, and Hye-In Kim(<i>Inha University, Korea</i>)	
14:10~ 14:30	Derivation of Precise Coordinates of 7 Permanent GNSS Stations of KIGAM <u>Byoungwook Kwak</u> ¹ *, Mutaek Lim ² , Yeongsue Park ² , Hyoungrae Rim ² , and Heejae Koh ² (¹ <i>Chungnam National University</i> , ² <i>Korea Institute of Geoscience and Mineral Resources, Korea</i>)	
13:30~ 15:10	FE3(Domestic): Precise navigation/Timing Chair : Prof. Young Jae Lee (<i>Konkuk Univ., Korea</i>)	201B
13:30~ 13:50	Prediction of GPS Clock using Grey Model <u>Youn-Jeong Heo</u> , Yearn-Gui Yi, Jeong-Ho Cho, and Moon-Beom Heo_(<i>KARI, Korea</i>)	
13:50~ 14:10	Cycle Slip Detection Methods in Precision Positioning Using GNSS Carrier Signal <u>Deokhee Han</u> ¹ , Seokbo Son ² , Chansik Park ¹ * and Eunjong Cha ¹ (¹ <i>Chungbuk National University</i> , ² <i>Hangyang Navicom Ltd., Korea</i>)	
14:10~ 14:30	Consideration on High Accuracy Correction Information for Precise Positioning <u>Deuk Jae Cho</u> *, Sang Hyun Park, and Sang Hyun Suh (<i>Korea Ocean Research & Development Institute, Korea</i>)	
15:10~15:30	Coffee Break	
15:30~15:50	Closing Ceremony(Location:201)	
15:50~16:10	Domestic Paper Award(Location:201)	